

RCP 10, 11: PI-controller

How energy efficiency is improved

Enables the implementation of individually optimised controls for maximum efficiency in pneumatic installations.

Areas of application

Pneumatic control in ventilation and air-conditioning equipment of temperature, pressure, pressure differential, humidity and flow rate in combination with appropriate transducers.

Features

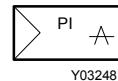
- PI fixed-value controller
- PI fixed-value/schedule controller
- Controllers can be used universally for the most varied of applications
- Housing, rack and front doors made of thermoplastic
- Suitable for wall or panel mounting
- Functional description and commissioning help inserted in front door
- Front panel with adjusters and 3 covered recesses for plug-in pressure gauge (XMP) making commissioning easier
- Setpoint adjuster X_S adjustable manually with scales for all Centair ranges
- All settings very easy to make with coin and % scale
- M4 measuring connections, control action adjustable (delivered with control action B)
- Rp $1/8$ " female thread
- Complies with directive 97/23/EC Art. 3.3 on pressure equipment

Technical description

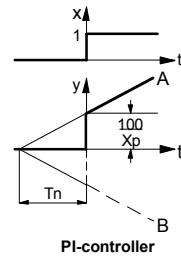
- Supply pressure 1.3 bar ± 0.1
- Easily accessible adjusters for X_S (setpoint), X_{P4} (P range), T_n (reset time), E (influence) and FF (schedule start point)
- Inputs for:
 - remote setpoint adjustment
 - controlled variable
 - command variable
- Outputs for:
 - output pressure for dampers or valve actuator



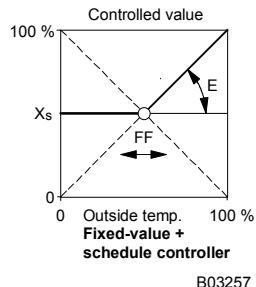
T03082



Y03248



B02214



B03257

Type	Description	Air capacity l _n /h	Air consumption ¹⁾ l _n /h	Weight kg
RCP 10 F001	fixed-value PI-controller	400	30	0,7
RCP 11 F001	fixed-value/schedule PI controller	400	30	0,7

RCP 10:	RCP 11:
Setpoint X_S	Setpoint X_S
Remote adjust. of setpoint	Remote adjustment of setpoint
P-band X_{P4}	0...100%
Reset time T_n	1...15 min
	Shift starting point FF
	Influence E
Supply pressure ²⁾	1,3 bar $\pm 0,1$
Input pressures	0,2...1,0 bar
Output pressures	0,2...1,0 bar
Permissible amb. temp.	0...55 °C
	Connection diagram, RCP 10
	Connection diagram, RCP 11
	Dimension drawing
	Fitting instructions

По вопросам продаж и поддержки обращайтесь:

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Екатеринбург +7 (343) 302-14-75
Ижевск +7 (3412) 20-90-75
Казань +7 (843) 207-19-05

Краснодар +7 (861) 238-86-59
Красноярск +7 (391) 989-82-67
Москва +7 (499) 404-24-72
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Operation

RCP 10 and RCP 11

The transducer at connection 4 converts the control variable into the pneumatic standard signal 0,2...1,0 bar (equivalent to 0...100%) within its measuring range. This actual-value signal x_{i4} is compared with the fixed setpoint X_s . If there is control deviation, the output pressure y is adjusted until the actual value is equal to the setpoint (PI-control). With a pressure of 0,2...1,0 bar at input 6, the setpoint can be set remotely from 0...100%. The internal setpoint setting then functions as a minimum limitation.

A restrictor ($\varnothing 0,2$ mm) for supplying the transducer is fitted at connection 4. The signals from the transducer and the output pressure can be checked via the M4 measuring connection or shown via the manometer.

RCP 11: additional functions

The transducer at connection 5 converts the command variable (e.g. outside temperature) into the pneumatic standard signal 0,2...1,0 bar (equivalent to 0...100%). This signal (x_{i5}) is fed to the command circuit which, together with the setting parameters FF and E, creates a program for the setpoint shift of the following PI-controller. The characteristic for the influence E can be placed in any of the four quadrants.

Because the outside temperature is often fed to more than one controller, the transducer at connection 5 must be supplied by a separate ($\varnothing 0,2$ mm) restrictor.

Additional details

RCP 10: Front plate with adjusters for setpoint, P-band and reset time.

RCP 11: Front plate with adjusters for setpoint, P-band, reset time, influence and shift starting point.

Additional information on accessories

0297103 000 Additional bag of eight alternative scales

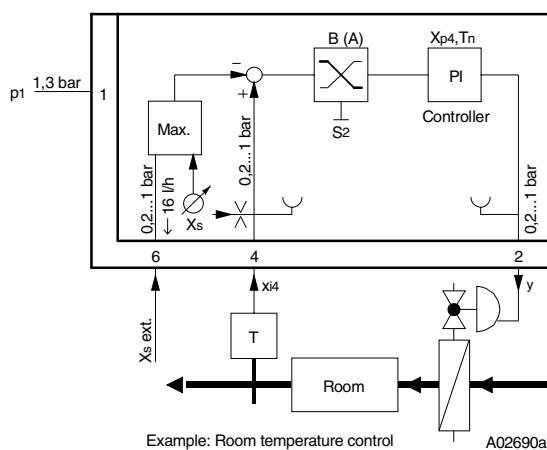
5...35 °C	20...90 %rh
-20...40 °C	0...5 mbar
0...120 °C	5...10 mbar
80...200 °C	10...15 mbar

Technical information

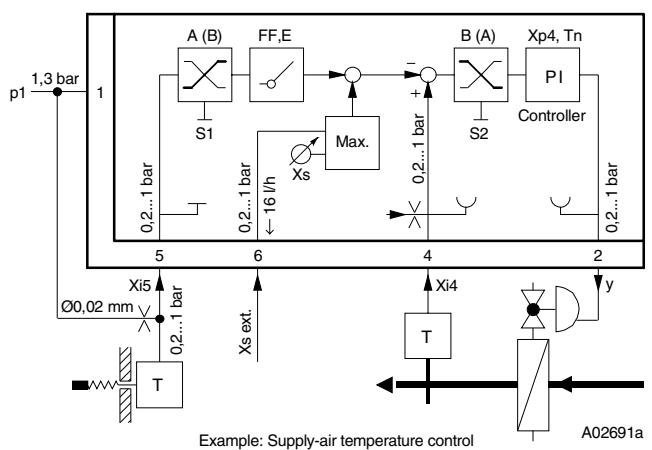
Technical manual: *centair* system 304991 003

Connection diagrams

RCP 10



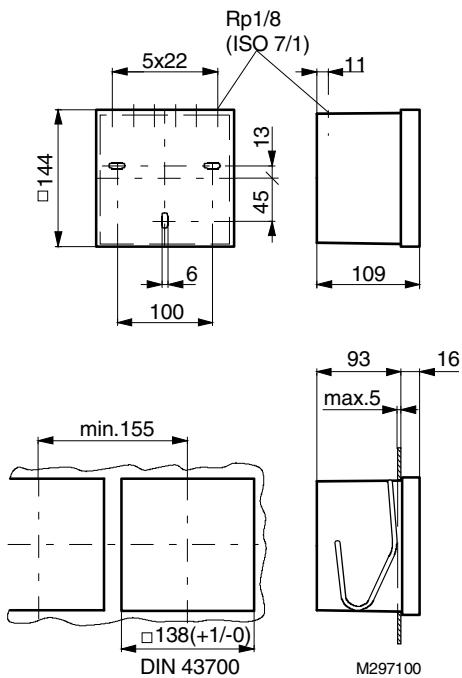
RCP 11



1	Supply pressure
2	Output pressure
4	Actual value for PI-controller
5	Command variable for fixed-value + schedule
6	Remote setpoint adjustment

T_n	Reset time
X_s	Variable setpoint
X_{P4}	P-band for PI-controller
FF	Shift starting point for fixed-value + schedule
E	Influence

x_{i4}	Control variable
x_{i5}	Command variable
y	Output pressure
S1	Control action for fixed-value + schedule
S2	Control action for controller

Dimension drawing

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